## SIMILARITY

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### Plan

- Invariance point/line
- Eigen value and eigen vectors
- Similarity
- Orthogonal similarity
- Minimum polynomial

#### **Reflection Transformation to X-axis**



R unchanged, R called invariant point. All of the points on X-axis are <u>invariant point</u>

### Reflection Transformation to Y-axis



R unchanged, R called invariant point. All of the points on Y-axis are <u>invariant point</u> Observe that on a transformation, it is possible there are any points or lines that unchanged by the transformation. Points or lines that unchanged by the transformations called <u>invariant points or invariant lines</u>.

### **Eigen value and eigen vector**

- Suppose  $X, Y \in \mathbb{R}^n$  and  $A_{n\times n}$  is transformation matrix.
- Generally behave Y=AX, it is mean that by transformation matrix A, a vector X tranformed to a vector Y.

Suppose 
$$\mathbf{A} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$
, a vector  $\mathbf{X} = \begin{pmatrix} 4 \\ 5 \end{pmatrix}$   
So  $\mathbf{AX} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 4 \\ 5 \end{pmatrix} = \begin{pmatrix} -4 \\ 5 \end{pmatrix} = \mathbf{Y}$ 

In special case, it is possible that a vector X transformed to the vector X (or its multiple), so :  $AX = \lambda X$ , where  $\lambda$  scalar on field F. In this case, X called eigen vector or invariant vector (vektor tetap) or characteristics vector.

Suppose 
$$\mathbf{A} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$
, if a vector  $\mathbf{X} = \begin{pmatrix} 0 \\ -7 \end{pmatrix}$   
Then  $\mathbf{AX} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ -7 \end{pmatrix} = \begin{pmatrix} 0 \\ -7 \end{pmatrix} = \mathbf{X}$ 

How to get a invariant vector X, such that:  $AX = \lambda X$ 

- $AX = \lambda X$ 
  - $\boldsymbol{AX} \lambda \boldsymbol{X} = \boldsymbol{0}$
  - $AX \lambda IX = 0$
  - $(\boldsymbol{A} \lambda \boldsymbol{I})\boldsymbol{X} = \boldsymbol{0}$  (2)

(1)

• System (2) will be had a nontrivial solution (penyelesaian tidak nol) *X*, if :

 $|\mathbf{A} - \lambda \mathbf{I}| = 0 \tag{3}$ 

Expanding equation (3) will be got a polynomial in λ, that is P(λ), it is called characteristics polynomial; thus characteristics polynomial is P(λ) = |A - λI|

- Because A and I are given, from the equation (3) where P(λ) = 0, it will be got values λ that called eigen values (akar karakteristik).
- Furthermore, if the value λ subtitute to the equation (2), it will be got eigen vectors (vektor invarian / vektor karakteristik) X.

### example

• Suppose a transformation matrix  $\mathbf{B} = \begin{pmatrix} -1 & 2 \\ 3 & 4 \end{pmatrix}$ 

Solution:  

$$\boldsymbol{B} - \lambda \boldsymbol{I} = \begin{pmatrix} -1 & 2 \\ 3 & 4 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 - \lambda & 2 \\ 3 & 4 - \lambda \end{pmatrix}$$

$$|\boldsymbol{B} - \lambda \boldsymbol{I}| = \begin{vmatrix} -1 - \lambda & 2 \\ 3 & 4 - \lambda \end{vmatrix} = \{(-1 - \lambda)(4 - \lambda)\} - (2)(3)$$

- $|\boldsymbol{B} \lambda \boldsymbol{I}| = (-2 \lambda)(5 \lambda)$
- $\mathsf{P}(\lambda) = |\boldsymbol{B} \lambda \boldsymbol{I}| = 0$
- $(-2-\lambda)(5-\lambda)=0$

 $\lambda_1 = -2$  and  $\lambda_2 = 5 \rightarrow Eigen value/$  $\rightarrow akar karakteristik$  Finding a eigen vectors can be done as follow:

For  $\lambda = -2$ , then :

$$(\boldsymbol{B} - \lambda \boldsymbol{I}) \boldsymbol{X} = \begin{pmatrix} -1 - \lambda & 2 \\ 3 & 4 - \lambda \end{pmatrix} \boldsymbol{X} = \begin{pmatrix} 1 & 2 \\ 3 & 6 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \boldsymbol{0}$$

$$(1 - 2) \boldsymbol{H} (1 - 2)$$

$$\begin{pmatrix} 1 & 2 \\ 3 & 6 \end{pmatrix} \stackrel{\mathsf{H}}{\sim} \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix} \quad \begin{array}{c} \mathsf{n} = 2 \\ \mathsf{r} = 1; \text{ number of free var} = 1 \end{array}$$

A New equation:  $x_1 + 2x_2 = 0$ 

Free variable:  $x_2$ suppose  $x_2 = \alpha \rightarrow x_1 = -2 \alpha$ 

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} -2\alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

So, the first eigen vector  $\mathbf{X}_1 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$ 

For  $\lambda = 5$ , then :

$$(\boldsymbol{B} - \lambda \boldsymbol{I}) \boldsymbol{X} = \begin{pmatrix} -1 - \lambda & 2 \\ 3 & 4 - \lambda \end{pmatrix} \boldsymbol{X} = \begin{pmatrix} -6 & 2 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \boldsymbol{0}$$

$$\begin{pmatrix} -6 & 2 \\ 3 & -1 \end{pmatrix} \mapsto \begin{pmatrix} -6 & 2 \\ 0 & 0 \end{pmatrix} = 2$$
 n= 1; number of free var=1

A new equation:  $-6x_1 + 2x_2 = 0$ ,

suppose 
$$x_2 = \alpha \rightarrow x_1 = \frac{1}{3}\alpha$$
  
 $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{3}\alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix}$ 

Thus, the second eigen vector  $\mathbf{X}_2 =$ 

$$= \begin{pmatrix} \frac{1}{3} \\ 1 \end{pmatrix}$$

### practice

• Suppose a transformation matrix  $\mathbf{B} = \begin{pmatrix} 3 & 2 \\ 1 & 2 \end{pmatrix}$ 

### Problems

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 2 & 2 \\ 2 & 1 & 2 \end{pmatrix}$$

$$\mathbf{B} = \begin{pmatrix} 1 & -1 & 0 \\ 1 & 2 & 1 \\ -2 & 1 & -1 \end{pmatrix}$$

$$\mathbf{F} = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

### **Properties :**

1) If  $\lambda_1$ ,  $\lambda_2$ ,..., and  $\lambda_k$  are the different eigen values and associated to the invariant vectors  $X_1$ ,  $X_2$ , ...,  $X_k$  respectively, then the invariant vectors are linearly independent.

2) Eigen values of the transformation matrix A and  $A^{T}$  are equal.

### example



## Solution: $\boldsymbol{A} - \boldsymbol{\lambda} \boldsymbol{I} = \begin{pmatrix} 2 & 2 & 1 \\ 1 & 3 & 1 \\ 1 & 2 & 2 \end{pmatrix} - \boldsymbol{\lambda} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 - \lambda & 2 & 1 \\ 1 & 3 - \lambda & 1 \\ 1 & 2 & 2 - \lambda \end{pmatrix}$ $|\mathbf{A} - \lambda \mathbf{I}| = \begin{vmatrix} 2 - \lambda & 2 & 1 \\ 1 & 3 - \lambda & 1 \\ 1 & 2 & 2 - \lambda \end{vmatrix} = (5 - \lambda)(1 - \lambda)(1 - \lambda)$

 $\mathsf{P}(\lambda) = |\mathbf{A} - \lambda \mathbf{I}| = 0$ 

 $P(\lambda) = (5 - \lambda)(1 - \lambda)(1 - \lambda) = 0$  $\lambda_{1,2} = 1 \text{ and } \lambda_3 = 5$ 

Next step, finding invariant vector, For  $\lambda = 1$ , then:

$$(\mathbf{A} - \lambda \mathbf{I}) \mathbf{X} = \begin{pmatrix} 2-\lambda & 2 & 1 \\ 1 & 3-\lambda & 1 \\ 1 & 2 & 2-\lambda \end{pmatrix} \mathbf{X} = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 2 & 1 \\ 1 & 2 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \mathbf{0}$$

$$\begin{pmatrix} 1 & 2 & 1 \\ 1 & 2 & 1 \\ 1 & 2 & 1 \end{pmatrix} \mathbf{H} \begin{pmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \mathbf{n} = \mathbf{3}$$

$$\mathbf{r} = \mathbf{1}; \text{ number of free var} = \mathbf{2}$$

A new equation :  $x_1 + 2x_2 + x_3 = 0 \rightarrow Free \text{ variables are:}$  $x_2 \text{ and } x_3$ 

### A new equation : $x_1 + 2x_2 + x_3 = 0$ suppose: $x_2 = \alpha$ and $x_3 = \beta \rightarrow$ then $x_1 = -2\alpha - \beta$

Thus, 
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{pmatrix} -2\alpha - \beta \\ \alpha \\ \beta \end{pmatrix} = \alpha \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

There are **two independent invariant vectors** :  $\mathbf{X}_1 = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$  and  $\mathbf{X}_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$  For  $\lambda = 5$ , then :

$$(\mathbf{A} - \lambda \mathbf{I}) \mathbf{X} = \begin{pmatrix} 2-\lambda & 2 & 1 \\ 1 & 3-\lambda & 1 \\ 1 & 2 & 2-\lambda \end{pmatrix} \mathbf{X} = \begin{pmatrix} -3 & 2 & 1 \\ 1 & -2 & 1 \\ 1 & 2 & -3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \mathbf{0}$$

 $\begin{pmatrix} -3 & 2 & 1 \\ 1 & -2 & 1 \\ 1 & 2 & -3 \end{pmatrix} \overset{\mathbf{H}}{\sim} \begin{pmatrix} 1 & -2 & 1 \\ -3 & 2 & 1 \\ 1 & 2 & -3 \end{pmatrix} \overset{\mathbf{H}}{\sim} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -4 & 4 \\ 0 & 4 & -4 \end{pmatrix} \overset{\mathbf{H}}{\sim} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -4 & 4 \\ 0 & 0 & 0 \end{pmatrix}$ 

n= 3 ; r = 2; number of free var = 1  $\rightarrow$  X<sub>1</sub> - 2X<sub>2</sub> + X<sub>3</sub> = 0 - 4X<sub>2</sub> + 4X<sub>3</sub> = 0 A new equations :  $x_1 - 2x_2 + x_3 = 0$ -  $4x_2 + 4x_3 = 0$ 

Free variable is  $x_3$ ; suppose:  $x_3 = \alpha \rightarrow$  then  $x_2 = \alpha$ , and  $x_1 = \alpha$   $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{pmatrix} \alpha \\ \alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ (1)

Thus, the third invariant vector  $X_3 =$ 

### **Problems**

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 2 \\ 0 & 2 & 2 \\ -1 & 1 & 3 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -3 & 3 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} -2 & 1 & 0 \\ -8 & 4 & 0 \\ -12 & 4 & 1 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} 2 & 2 & 0 \\ 2 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{C} = \begin{pmatrix} -3 & -9 & -12 \\ 1 & 3 & 4 \\ 0 & 0 & 1 \end{pmatrix}$$

similarity

### Recall your mind

$$\mathbf{A} = \begin{pmatrix} 2 & 2 & 1 \\ 1 & 3 & 1 \\ 1 & 2 & 2 \end{pmatrix}$$

$$\mathbf{B} = \begin{pmatrix} 5 & 14 & 13 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



# $\boldsymbol{A} = \begin{pmatrix} 2 & 2 & 1 \\ 1 & 3 & 1 \\ 1 & 2 & 2 \end{pmatrix} \quad \text{and } \boldsymbol{B} = \begin{pmatrix} 5 & 14 & 13 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{are similar}$

becuase there is non singular matrix

$$\mathbf{P} = \begin{pmatrix} 1 & 3 & 3 \\ 1 & 4 & 3 \\ 1 & 3 & 4 \end{pmatrix}$$
, such that  $\mathbf{B} = \mathbf{P}^{-1}\mathbf{A}\mathbf{P}$ .

### Similarity

 Two Transformations matrix A and B called similar if there is nonsingular matrix R such that
 B = R<sup>-1</sup>AR

### Properties

1) Two similar matrices have same eigen values.

2) if **Y** is eigen vector of **B** which is associated to eigen value  $\lambda_i$ , then **X** = **RY** is eigen vector of **A** which is associated to eigen value  $\lambda_i$ .
The current problems : If there are any two matrix *A* and *B*, how to get a nonsingular matrix *P* such that  $P^{-1}AP = B$ ? Now, please find eigen values and eigen vectors of

$$\mathbf{D} = \begin{pmatrix} 5 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -3 \end{pmatrix}$$

#### **Diagonal Matrix**

$$\mathbf{D} = \begin{pmatrix} -3 & 0 & 0 \\ 0 & 7 & 0 \\ 0 & 0 & 9 \end{pmatrix}.$$
 Eigen value of matrix **D** are  $\lambda_1 = -3, \lambda_2 = 7$ ,

and  $\lambda_3 = 9$ . Eigen vectors are

$$\begin{pmatrix} 1\\0\\0 \end{pmatrix}, \begin{pmatrix} 0\\1\\0 \end{pmatrix}, \text{ and } \begin{pmatrix} 0\\0\\1 \end{pmatrix}.$$

Every nxn diagonal matrix have *n* eigen vectors which are linearly independent.

Similar to Diagonal Matrices: Diagonalization of Matrices

• Theorem:

every *n-dimensional* matrix A which have *n* eigen vectors that linearly independence are similar to diagonal matrix.

#### Proof:

Suppose  $X_1, X_2, X_3, ..., X_n$  are invariant vectors which are associated to the eigen value  $\lambda_1, \lambda_2, \lambda_3, ..., \lambda_n$  such that  $AX_i = \lambda_i X_i$  (*i* = 1, 2, 3, ..., *n*). Suppose  $P = [X_1 \ X_2 \ X_3 \dots \ X_n]$ , then  $AP = A[X_1 \ X_2 \ X_3 \ \dots \ X_n] = [AX_1 \ AX_2 \ AX_3 \ \dots \ AX_n]$  $AP = \begin{bmatrix} \lambda_1 X_1 & \lambda_2 X_2 & \lambda_3 X_3 & \dots & \lambda_n X_n \end{bmatrix}$ 

# $\mathbf{Proof...}(\mathbf{cont..})$ $\mathbf{AP} = [\mathbf{X}_1 \ \mathbf{X}_2 \ \mathbf{X}_3 \ \dots \ \mathbf{X}_n] \begin{pmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 \\ 0 & 0 & \lambda_3 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & \lambda_n \end{pmatrix}$

 $AP = [X_1 \ X_2 \ X_3 \ \dots \ X_n] \operatorname{diag}(\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_n)$ AP = P D $P^{-1}AP = P^{-1}P D$  $P^{-1}AP = D$ 

Thus, *A* similar to diagonal matrix D, because there is nonsingular matrix P such that  $P^{-1}AP = D$ .

• A matrices **A**<sub>nxn</sub> which have *n* invariant vectors that linearly independence called diagonalizable (it can be diagonalized / similar to diagonal matrices).

#### Algorithm for diagonalization of matrix *Anxn* :

- (1) find eigen value of matrix **A**, that are  $\lambda_i$  (*i* =1,2, 3, ..., *n*)
- (2) Find eigen vectors of matrix **A** which are associated to eigen value  $\lambda_i$ .
- (3) if a <u>number of eigen vectors</u> < n, then matrix A is not diagonalizable. Finish.
- (4) If a <u>number of eigen vectors</u> = n, then matrix A is diagonalizable; next step:
  - (4.1). Take  $P = [X1 \ X2 \ X3 \ ... \ Xn]$ , where  $X_i$  are eigen vectors of matrix A.
  - (4.2). Find **P**<sup>-1</sup>
  - (4.3).  $P^{-1}AP = D = \text{diag}(\lambda_1, \lambda_2, \lambda_3, ..., \lambda_n)$ , with  $\lambda_i$  are eigen value of matrix **A**.
  - (4.4). Finish.

#### example

Is a matrix 
$$A = \begin{pmatrix} 2 & 1 \\ 2 & 3 \end{pmatrix}$$
 diagonalizable ?. if yes, find matrices

P such that  $P^{-1}AP = D$  (diagonal).

#### Solution:

• Finding eigen value:  $|A - \lambda I| = \begin{vmatrix} 2 - \lambda & 1 \\ 2 & 3 - \lambda \end{vmatrix} = 0$ 

thus the eigien value are  $\lambda_1 = 1$  and  $\lambda_2 = 4$ .

• Finding eigen vectors:

For  $\lambda = 1$ , then  $(A - \lambda I)X = 0$  $\begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$ 

the first eigen vector is  $\boldsymbol{X}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$ 

For  $\lambda = 4$ , then  $(\mathbf{A} - \lambda \mathbf{I})\mathbf{X} = 0$  $\begin{pmatrix} -2 & 1 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$ the second eigen vector is  $\mathbf{X}_2 = \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix}$ 

Because matrix **A** have <u>two independent</u> <u>invariant vectors</u>, the matrix **A** is diagonalizable.

• 
$$\mathbf{P} = (\mathbf{X}_1 \ \mathbf{X}_2) = \begin{pmatrix} -1 & \frac{1}{2} \\ 1 & 1 \end{pmatrix}$$

Finding inverse of P

$$\mathbf{P}^{-1} = \begin{pmatrix} -\frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{2}{3} \end{pmatrix}$$

It can be verified that : P<sup>-1</sup> A P = D.

$$\mathbf{P^{-1} A P} = \begin{pmatrix} -\frac{2}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{2}{3} \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} -1 & \frac{1}{2} \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix} = \mathbf{D}.$$

#### example

• Is a matrix **B** = 
$$\begin{pmatrix} 2 & 2 & 1 \\ 1 & 3 & 1 \\ 1 & 2 & 2 \end{pmatrix}$$

diagonalizable ?

if yes, find a nonsingular matrices **P** such that  $P^{-1}BP = D$  (Diagonal).

#### Solution:

From slide 21 to slide 26, it can be observed:

- Eigen value are  $\lambda_{1,2} = 1$  and  $\lambda_3 = 5$ .
- For  $\lambda = 1$ , the eigen vectors are :

$$\mathbf{X}_{1} = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix}$$
 and  $\mathbf{X}_{2} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$ 

For  $\lambda$  = 5, the eigen vector is :

$$\mathbf{X}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

Because a matrix **B** have three independent invariant vectors, the matrix **B** is **diagonalizable**.

• 
$$\mathbf{P} = (\mathbf{X}_1 \ \mathbf{X}_2 \ \mathbf{X}_3) = \begin{pmatrix} -2 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

• 
$$\mathbf{P}^{-1} = \frac{1}{4} \begin{pmatrix} -1 & 2 & -1 \\ -1 & -2 & 3 \\ 1 & 2 & 1 \end{pmatrix}$$

• 
$$\mathbf{P}^{-1}\mathbf{B}\mathbf{P} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{pmatrix} = \mathbf{D}.$$

#### example

- Is a matrix  $\mathbf{C} = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 2 & 2 \\ 2 & 1 & 2 \end{pmatrix}$  diagonalizable?.
  - If yes, find a matrix **P** such that **P**<sup>-1</sup>**CP** = **D** (Diagonal).

#### Solution:

- The eigen value of **C** are  $\lambda_1 = 1$  and  $\lambda_{2,3} = 2$ .
- For  $\lambda = 1$ , the eigen vector is  $X_1 = \begin{pmatrix} -\frac{1}{2} \\ 1 \\ 0 \end{pmatrix}$ For  $\lambda = 2$ , the eigen vector is  $X_2 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$
- Because the matrix C are only have two independent vectors, the matrix C is not diagonalizable.

• Is a matrix  $A = \begin{pmatrix} 3 & -2 \\ -2 & 6 \end{pmatrix}$  diagonalizable ? if yes, find a nonsingular matrices P such that  $P^{-1}AP = D$  (Diagonal).

Is a matrix 
$$A = \begin{pmatrix} 1 & 1 & 2 \\ 0 & 2 & 2 \\ -1 & 1 & 3 \end{pmatrix}$$
 diagonalizable ?. if yes, find

matrices P such that  $P^{-1}AP = D$  (diagonal).

 Is F diagonalizable?, if yes, find matrices R such that R<sup>-1</sup>FR = D

$$F = \begin{pmatrix} 3 & 1 & 1 \\ 2 & 4 & 2 \\ 1 & 1 & 3 \end{pmatrix}$$

• Is a matrix B = 
$$\begin{pmatrix} 2 & -4 & 2 \\ -4 & 2 & -2 \\ 2 & -2 & -1 \end{pmatrix}$$
 diagonalizable ?

if diagonalizable, find a nonsingular matrices P such that  $P^{-1}BP = D$  (Diagonal).

#### problem

 Is a matrix *C* diagonalizable ?. If diagonaliozable, find a matrices *R* such that *R*<sup>-1</sup>*CR* = *D*.

$$C = \begin{pmatrix} 1 & 2 & 0 \\ 2 & 2 & 2 \\ 0 & 2 & 3 \end{pmatrix}$$

## Orthogonal Similarity

### Similarity of Symmetric matrices

- If A is a symmetric matrices, that is A<sup>T</sup> = A, it can be found an orthogonal matrices R such that R<sup>-1</sup>AR = D (diagonal).
- Because if **R** is orthogonal,  $\mathbf{R}^{-1} = \mathbf{R}^{\mathsf{T}}$  thus  $\mathbf{R}^{-1}\mathbf{A}\mathbf{R} = \mathbf{R}^{\mathsf{T}}\mathbf{A}\mathbf{R} = \mathbf{D}$

## Theorem

Eigen vectors of a symmetric matrices which come from the different eigen value are orthogonal

#### Proof:

Suppose  $X_1$  and  $X_2$  are invariant vectors which are associated to  $\lambda_1$  and  $\lambda_2$  (where  $\lambda_1 \neq \lambda_2$ ) of symmetric matrices A, then :  $AX_1 = \lambda_1 X_1$  $X_2^T A X_1 \equiv X_2^T \lambda_1 X_1$ (1) $(X_2^T A X_1)^T \equiv (\lambda_1 X_2^T X_1)^T$  $X_1^T A^T X_2 = \lambda_1 X_1^T X_2$  $X_1^T A X_2 = \lambda_1 X_1^T X_2$ (2)

#### proof...(*cont*..)

Meanwhile :

 $AX_2 = \lambda_2 X_2$  $X_1^T \mathbf{A} \mathbf{X}_2 = \lambda_2 X_1^T \mathbf{X}_2$ (3) $(X_1^T A X_2)^T = (\lambda_2 X_1^T X_2)^T$  $X_2^T \mathbf{A}^T \mathbf{X}_1 = \lambda_2 X_2^T \mathbf{X}_1$  $X_2^T \mathbf{A} \mathbf{X}_1 = \lambda_2 X_2^T \mathbf{X}_1$ (4)from (2) and (3) :  $\lambda_1 X_1^T \mathbf{X}_2 = \lambda_2 X_1^T \mathbf{X}_2$  $\lambda_1 X_1^T \mathbf{X}_2 - \lambda_2 X_1^T \mathbf{X}_2 = 0$  $(\lambda_1 - \lambda_2) X_1^T X_2 = 0 \text{ or } X_1^T X_2 = 0$ This mean that  $X_1$  orthogonal to  $X_2$ .

#### Consequence...

For a symmetric matrices, The theorem above assure of an existence of orthogonal matrices *R*, such that *R<sup>T</sup>AR = D*.

For a symmetric matrices A, algorithm to find orthogonal matrices R such that R<sup>-1</sup>AR = D (diagonal) as follow:

- (1) Find eigen value of matrix **A**
- (2) Find invariant vectors of matrix A
- (3) If all of the eigen values are different, then invariant vectors X1, .., Xn are orthogonal.
  - (3.1) normalized X1, ..., Xn become new vectors Y1, Y2,..., Yn.
  - (3.2) orthogonal matrix **R** = [Y1 Y2 ... Yn].
- (4) If there are same eigen value, suppose  $\lambda_1 = \lambda_2$ , then eigen vector X1 and X2 are not orthogonal; but eigen vectors X3, ..., Xn are orthogonal.
  - (4.1) apply Gram-Schmidt process to X1 and X2 to get a new orthogonal vectors W1 and W2.
  - (4.2) take W3 = X3, ..., Wn = Xn
  - (4.3) normalized vectors W1, W2, W3, ..., Wn become a new vectors Y1, Y2, Y3, .., Yn.
  - (4.4) orthogonal matrix **R** = [Y1 Y2 ... Yn].
  - (4.5) *R*<sup>-1</sup>*AR* **= <b>***D* (diagonal). finish.

#### example

 find an orthogonal matrices *R* such that *R*<sup>-1</sup>*AR* = *D* (diagonal), if

$$A = \begin{pmatrix} -4 & -6 \\ -6 & 1 \end{pmatrix}$$

#### Solution:

- Observe that A is symmetric, because A<sup>T</sup> = A
- The eigen value of **A** are  $\lambda_1 = 5$  and  $\lambda_2 = -8$  For  $\lambda_1 = 5$ , the eigen vector  $\mathbf{X}_1 = \begin{pmatrix} -\frac{2}{3} \\ 1 \end{pmatrix}$

- For  $\lambda_2 = -8$ , the eigen vector  $\mathbf{X}_2 = \begin{pmatrix} \frac{3}{2} \\ 1 \end{pmatrix}$  Observe that  $\mathbf{X}_1$  and  $\mathbf{X}_2$  are orthogonal,  $\mathbf{X}_1 \cdot \mathbf{X}_2 = 0$ .
- Normalize X<sub>1</sub> and X<sub>2</sub>

$$\mathbf{g_1} = \frac{\mathbf{X}_1}{\|\mathbf{X}_1\|} = \begin{pmatrix} -\frac{2}{\sqrt{13}} \\ \frac{3}{\sqrt{13}} \end{pmatrix} \text{ , and } \mathbf{g_2} = \frac{\mathbf{X}_2}{\|\mathbf{X}_2\|} = \begin{pmatrix} \frac{3}{\sqrt{13}} \\ \frac{2}{\sqrt{13}} \end{pmatrix}$$

• Orthogonal matrix **R** = (**g**<sub>1</sub> **g**<sub>2</sub>) = 
$$\begin{pmatrix} -\frac{2}{\sqrt{13}} & \frac{3}{\sqrt{13}} \\ \frac{3}{\sqrt{13}} & \frac{2}{\sqrt{13}} \end{pmatrix}$$

• 
$$\mathbf{R}^{-1} = \mathbf{R}^{\mathsf{T}} = \begin{pmatrix} -\frac{2}{\sqrt{13}} & \frac{3}{\sqrt{13}} \\ \frac{3}{\sqrt{13}} & \frac{2}{\sqrt{13}} \end{pmatrix}$$

It can be verified that R<sup>-1</sup>AR = D

$$\begin{pmatrix} -\frac{2}{\sqrt{13}} & \frac{3}{\sqrt{13}} \\ \frac{3}{\sqrt{13}} & \frac{2}{\sqrt{13}} \end{pmatrix} \begin{pmatrix} -4 & -6 \\ -6 & 1 \end{pmatrix} \begin{pmatrix} -\frac{2}{\sqrt{13}} & \frac{3}{\sqrt{13}} \\ \frac{3}{\sqrt{13}} & \frac{2}{\sqrt{13}} \end{pmatrix} = \begin{pmatrix} 5 & 0 \\ 0 & -8 \end{pmatrix}$$

#### example

find orthogonal matrices *P* such that
*P<sup>T</sup>LP* = *D* (diagonal), if

$$\mathbf{L} = \begin{pmatrix} 7 & -2 & 1 \\ -2 & 10 & -2 \\ 1 & -2 & 7 \end{pmatrix}$$

#### Solution:

- Observe that L is symmetric, because L<sup>T</sup> = L
- The eigen value of L are  $\lambda_{1,2} = 6$  and  $\lambda_3 = 12$

• For  $\lambda = 6$ , the eigen vector  $\mathbf{X}_1 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$  and  $\mathbf{X}_2 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$ For  $\lambda = 12$ , the third eigen vector  $\mathbf{X}_3 = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ 

Observe that X<sub>1</sub> and X<sub>3</sub> are orthogonal, X<sub>1</sub>.X<sub>3</sub> = 0; beside X<sub>2</sub> and X<sub>3</sub> are also orthogonal, X<sub>2</sub>.X<sub>3</sub> = 0. Meanwhile X<sub>1</sub> and X<sub>2</sub> are not orthogonal, why?

Now, use gram-schmidt process to make X<sub>1</sub> and X<sub>2</sub> orthogonal:

$$w_1 = X_1 = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$$
 and  $w_2 = X_2 - \frac{X_2 \cdot X_1}{X_1 \cdot X_1} X_1 = \begin{pmatrix} -\frac{1}{5} \\ \frac{2}{5} \\ 1 \end{pmatrix}$ 

and also take 
$$w_2 = X_3 = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$$
 (why?).

Normalize w<sub>1</sub>, w<sub>2</sub>, and w<sub>3</sub> become g<sub>1</sub>, g<sub>2</sub>, and g<sub>3</sub> respectively, thus:
$$\mathbf{g}_{1} = \begin{pmatrix} \frac{2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \\ 0 \end{pmatrix}, \quad \mathbf{g}_{2} = \begin{pmatrix} -\frac{1}{\sqrt{30}} \\ \frac{2}{\sqrt{30}} \\ \frac{5}{\sqrt{30}} \end{pmatrix}, \text{ and } \mathbf{g}_{3} = \begin{pmatrix} \frac{1}{\sqrt{6}} \\ -\frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{6}} \end{pmatrix}$$
$$\mathbf{P} = (\mathbf{g}_{1} \, \mathbf{g}_{2} \, \mathbf{g}_{3}) = \begin{pmatrix} \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{30}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{30}} & -\frac{2}{\sqrt{6}} \\ 0 & \frac{5}{\sqrt{30}} & \frac{1}{\sqrt{6}} \end{pmatrix}$$

• It can be shown that 
$$\mathbf{P}^{\mathsf{T}}\mathbf{L}\mathbf{P} = \begin{pmatrix} 6 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 12 \end{pmatrix} = \mathbf{D}$$

#### practice

find an orthogonal matrices *R* such that
*R*<sup>-1</sup>*AR* = *D* (diagonal)

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 2 \\ 2 & 1 & 2 \\ 2 & 2 & 1 \end{pmatrix}$$

#### problem

find an orthogonal matrices *R* such that
*R<sup>T</sup>BR* = *D* (diagonal)

$$\mathsf{B}=\begin{pmatrix} 2 & 0 & -1\\ 0 & 2 & 0\\ -1 & 0 & 2 \end{pmatrix}$$

#### practice

find an orthogonal matrices *R* such that
*R<sup>T</sup>CR* = *D* (diagonal)

$$\mathbf{C} = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 3 & 0 \\ 1 & 0 & 2 \end{pmatrix}$$

#### problems

find an orthogonal matrices *R* such that
*R*<sup>-1</sup>*ER* = *D* (diagonal)

$$\mathbf{E} = \begin{pmatrix} 3 & 2 & 2 \\ 2 & 2 & 0 \\ 2 & 0 & 4 \end{pmatrix}$$

find an orthogonal matrices *R* such that
*R<sup>T</sup>FR* = *D* (diagonal), if

$$\mathbf{F} = \begin{pmatrix} 4 & -1 & 1 \\ -1 & 4 & -1 \\ 1 & -1 & 4 \end{pmatrix}$$

find an orthogonal matrices *R* such that
*R<sup>T</sup>GR* = *D* (diagonal), if

$$\mathbf{G} = \begin{pmatrix} 3 & 1 & 1 \\ 1 & 0 & 2 \\ 1 & 2 & 0 \end{pmatrix}$$

find orthogonal matrices *R* such that
*R*<sup>-1</sup>*HR* = *D* (diagonal), if

$$H = \begin{pmatrix} 2 & 2 & 2 \\ 2 & 5 & 4 \\ 2 & 4 & 5 \end{pmatrix}$$

find orthogonal matrices *R* such that
*R*<sup>-1</sup>*KR* = *D* (diagonal), if

$$\mathbf{K} = \begin{pmatrix} 7 & -4 & -4 \\ -4 & 1 & -8 \\ -4 & -8 & 1 \end{pmatrix}$$

# Minimum Polynomial

## **Characteristics Polynomial**

Suppose given a *nxn* matrix **A**:

- Characteristics Polynomial of **A** is  $P(\lambda) = |\mathbf{A} - \lambda \mathbf{I}|$
- From properties of adjoint matrices:

• Analogy :  $(\mathbf{A} - \lambda \mathbf{I}) \operatorname{adj}(\mathbf{A} - \lambda \mathbf{I}) = |\mathbf{A} - \lambda \mathbf{I}| \mathbf{I}$  $(\mathbf{A} - \lambda \mathbf{I}) \operatorname{adj}(\mathbf{A} - \lambda \mathbf{I}) = P(\lambda) \mathbf{I}$ 

# Theorem:

• Every *n*-dimensional square matrices A is zero value of it characteristic polynomial.  $\rightarrow$  Thus, if P( $\lambda$ ) = |**A** -  $\lambda$ **I**|, then P(**A**) = **0**.

#### example:



- $P(\lambda) = |A \lambda I| = (2 \lambda)(1 \lambda) 6 = \lambda^2 3\lambda 4$
- $\mathbf{P}(\mathbf{A}) = \mathbf{A}^2 3\mathbf{A} 4\mathbf{I} = \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix}^2 3 \begin{pmatrix} 2 & 3 \\ 2 & 1 \end{pmatrix} 4 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
- $\mathbf{P}(\mathbf{A}) = \begin{pmatrix} 10 & 9 \\ 6 & 7 \end{pmatrix} \begin{pmatrix} 6 & 9 \\ 6 & 3 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \mathbf{0}.$

# Minimum Polynomial

• Suppose  $P(\lambda)$  is characteristics polynomial of square matrices A, if  $m(\lambda)$  which is least degree of those polynomial such that m(A) = 0, then  $m(\lambda)$  called minimum polynomial of **A**.

### Algorithm for Finding Minimum Polynomial

- If  $\mathbf{A} = a_0 \mathbf{I}$ , then  $m(\lambda) = \lambda a_0$
- If  $\mathbf{A} \neq \mathbf{a}_0 \mathbf{I}$  for all  $\mathbf{a}_0$ , but  $\mathbf{A}^2 = \mathbf{a}_1 \mathbf{A} + \mathbf{a}_0 \mathbf{I}$ , then m( $\lambda$ ) =  $\lambda^2 - \mathbf{a}_1 \lambda - \mathbf{a}_0$ .
- If  $\mathbf{A}^2 \neq a_1 \mathbf{A} + a_0 \mathbf{I}$  for all  $a_1$  and  $a_0$ , but  $\mathbf{A}^3 = a_2 \mathbf{A}^2 + a_1 \mathbf{A} + a_0 \mathbf{I}$ , then minimum polynomial is  $m(\lambda) = \lambda^3 a_2 \lambda^2 a_1 \lambda a_0$ .
- etc.

# **Trial and Error Method**

By finding factors of P(λ), so m(λ) is one of the factors of P(λ), such that m(A) = 0.

#### example

• Find minimum polynomial of :

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 2 \\ 1 & 1 & 2 \\ 1 & 1 & 2 \end{pmatrix}$$

## Solution:

• The characteristics polynomial of **A** is

$$\mathsf{P}(\lambda) = |\mathbf{A} - \lambda \mathbf{I}| = \begin{vmatrix} 1 - \lambda & 1 & 2 \\ 1 & 1 - \lambda & 2 \\ 1 & 1 & 2 - \lambda \end{vmatrix} = (\mathbf{4} - \lambda) \lambda^2$$

- The possibilities of minimum polynomial are : (4 - λ), or λ<sup>2</sup>, or (4 - λ) λ; but only polynomial m(λ) = (4 - λ) λ satisfying the condition : m(A) = (4I - A) A = 0.
- Thus, the minimum polynomial is  $m(\lambda) = (4 - \lambda) \lambda = 4\lambda - \lambda^2$